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Design for reduction EMI of flyback switching power supply 1891
Theirakul Chaivat and Prempraneerach Yothin

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Receding Horizon Finite Memory Controls for Output Feedback Controls of Discrete-Time State Space Models 1896

Kwon Wook Hyun and Han Soo Hee

A Globally Stabilizing Model Predictive Control for Neutrally Stable Discrete-Time Linear Systems with Input Constraints 1901

Yoon Tae-Woong, Kim Jung-Su, Ali Jadbabaie and Claudio De Persis

Constrained MPC for uncertain time-delayed systems 1905

Park PooGyeon and Jeong SeungCheol

Feasible and Invariant Sets for Input Constrained Linear Parameter Varying Systems 1911

Lee Young Il

FP04 : Robot Navigation II

An Aerial Robot System Tracking a Moving Object 1917

OGATA Takehito, TAN Joo Kooi and ISHIKAWA Seiji

Local Minimum Free Motion Planning for Mobile Robots within Dynamic Environments 1921

Choi Jong-Suk, Kim Munsang and Lee Chong-won

Simplified Cooperative Collision Avoidance Method Considering the Desired Direction as the Operation Objective of Each Mobile Robot 1927

ABE Yasuaki and MATSUO Yoshiki

A Covariance Matrix Estimation Method for Position Uncertainty of the Wheeled Mobile Robot 1933

Doh Nakju, Chung Wan Kyun and Youm Youngil

A Shortest Path Planning Algorithm for Mobile Robots Using a Modified Visibility Graph Method 1939

Lee Duk-Young, Koh Kyung-Chul and Cho Hyungsuck

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Controlled Inquiry Rates of Clinical Interviews in Telehomecare 1945

Moskowitz Samuel E.

Drug dose control for nonlinear dynamics of HIV infection: receding horizon control 1951

Shim Hyungbo, Han Seung Ju, Jeong Inseok, Huh Young Hee, Chung Chungchoo, Nam Sangwon and Seo Jinwon

Modeling of Heart Phantom using the Multidipole Current Source. 1957

Yoon DalHwan and Jang KwanHee

Communication device to use slight body movement for ALS patients. 1963

Fukuda Yoshio, Tanaka Motohiro, Yamanaka Yuuki and Ishimatsu Takakazu

Monitoring system of physical behavior for dementia patient 1968

Tanaka Motohiro, Murakami Ryuya, Lue Xiao Dong and Ishimatsu Takakazu

Application of 3-D scanner to analysis of functional instability of the ankle 1971

Han ChengChun, Masakazu Kubo, Nobuo Matsusaka and Takakazu Ishimatsu

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Design and Experimental Report for the Special 3D.O.F Robot Manipulator	2000
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Compliance Analysis and Vibration Control of the Safe Arm with MR-based Passive Compliant Joints	2010
<i>Yun Seungkook, Yoon SeongSik, Kang Sungehul, Yeo Inteak, Kim Munsang and Lee Chongwon</i>	
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<i>Roh Se-gon, Park Kiheung, Yang KwangWoong, Park JinHo, Kim Hongseok, Lee Ho-Gil and Choi Hyoukryeol</i>	
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