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TE07-4	Control of an Artificial-Hip-Joint Simulator to Evaluate Dislocation Kazuo Kiguchi, Akira Yamashita, Makoto Sasaki, Masaru Ueno, Tsuneyuki Kobayashi, Masaaki Mawatari and Takao Hotokebuchi	1942
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TE08-3	AROMS: A Real-time Open Middleware System for Controlling Industrial Plant Systems Kee-Young Shin and Hwa-Won Hwang	1961
TE08-4	The Potential for Material Processing by Microwave Energy	1966

TE08-5	Yeongseob Kueon Ultrasonic Plate Wave Properties in Thin Steel Plates Sang-Woo Choi, GooHwa Kim, Jinsu Bae and Kwan-Tae Kim	1972
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TE09-2	A real-time eye tracking system using fast feature matching algorithm Young Shin Lim, Joon Seek Kim and Hyonam Joo	1981
TE09-3	De-blurring Algorithm for Fish Eye Image on CCTV with Nonlinear Equation In Jeong Lee	1986

TE10 : OS023 Assistive Robotics

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TE10-2	Design of Seat Mechanism for Multi-Posture-Controllable Wheelchair Ju-hwan Bae and Inhyuk Moon	1994
TE10-3	Computer controlled training system for standing up motion Yoji Nishi, Tadasuke Matsumoto, Shunji Moromugi, Takakazu Ishimatsu, Taichi Sakamoto and Takanori Nagano	1998
TE10-4	Smart Suit: Soft Power Suit with Semi-active Assist Mechanism Takayuki Tanaka, Yuta Satoh, Shunji Kaneko, Yoshihito Suzuki, Naohisa Sakamoto and Shuji Seki	2002
TE10-5	Grip Force Modeling of a Tendon-driven Prosthetic Hand Sung-yoon Jung and Inhyuk Moon	2006
TE10-6	Treatment Apparatus Employing Air-Bag Actuation for Sleep Apnea Syndrome Daichi Sakamoto, Yusuke Tomimatsu, Shunji Moromugi, Takakazu Ishimatsu and Takao Ayuse	2010

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TEP-2	Multi-Dimensional Emotional Engine with Personality Using Intelligent Service Robot for Children Ho Seok Ahn, Young Min Baek, Jin Hee Na and Jin Young Choi	2020
TEP-3	Mechanism and Control of Biped Walking Robot with 3 DOF Waist Kensuke Tajima and Hun-ok Lim	2026
TEP-4	Development of Collision Force Suppression Mechanism Masahiko Sunagawa and Hun-ok Lim	2032
TEP-5	Implementation of Dialogue System for Intelligent Service Robots Changyoon Lee, You-Sung Cha and Tae-Yong Kuc	2038
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